

FIG

# FIG WORKING WEEK 2017

Helsinki Finland

29 May - 2 June 2017

Presented at the FIG Working Week 2017,  
May 29 - June 2, 2017 in Helsinki, Finland



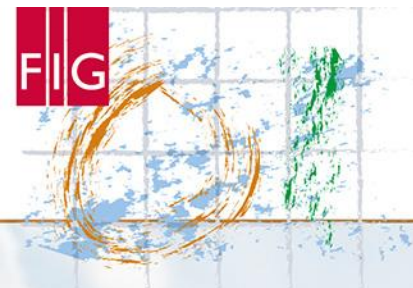
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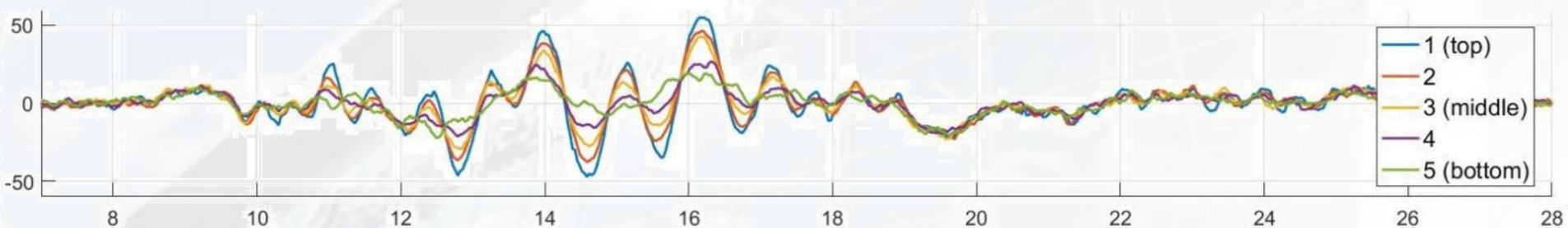
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## Monitoring Masonry Walls Subjected to Earthquake Loading with a ToF Range Camera

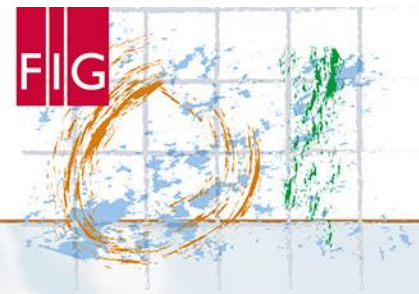
David Holdener, Derek D. Lichti, Jeremy Steward and Pedram Kaheh  
University of Calgary, Canada



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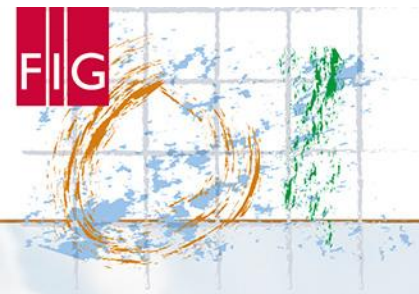
## Motivation

- Masonry buildings are at risk of collapsing during earthquakes
- Reducing this risk by applying repair material
- Structural loading tests to assess the effectiveness of the material



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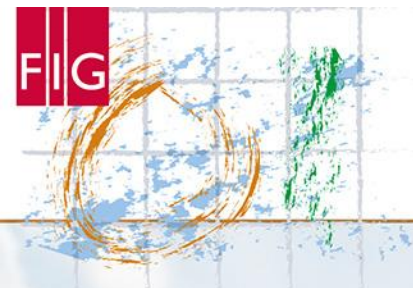
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## Research Objectives

- Monitoring the experiments using a ToF range camera
- Delivering additional 3D information
- Applicability of range sensors for structural loading tests





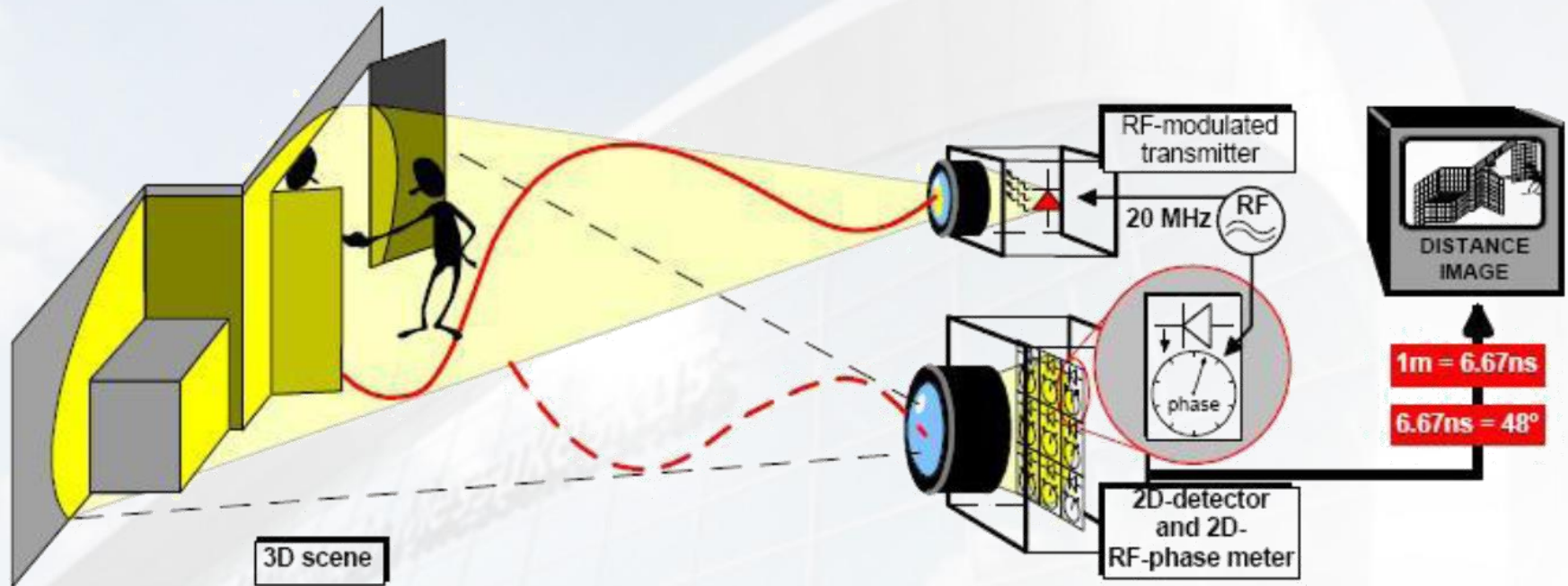
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## Time-of-Flight Range Camera Principle



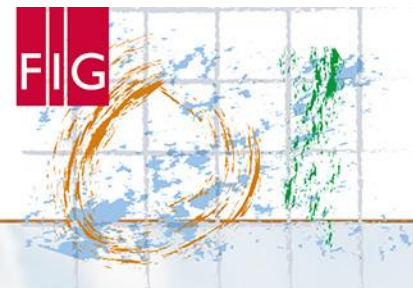
Lange, R. and Seitz, P., 2001. Solid-State Time-of-Flight Range Camera. *IEEE Journal of Quantum Electronics*, 37(3), pp.390–397.



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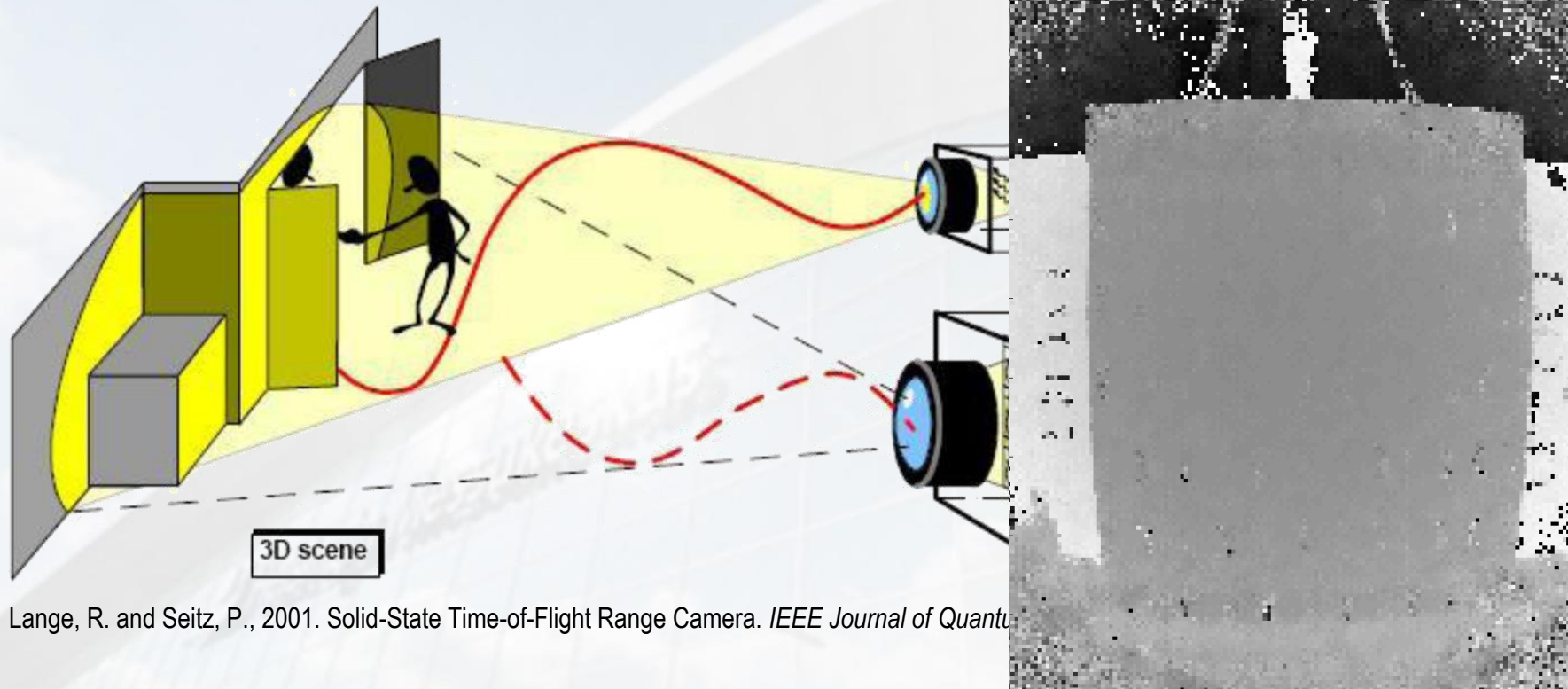
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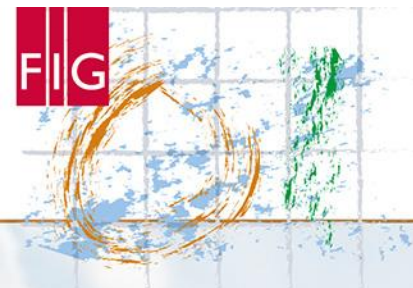


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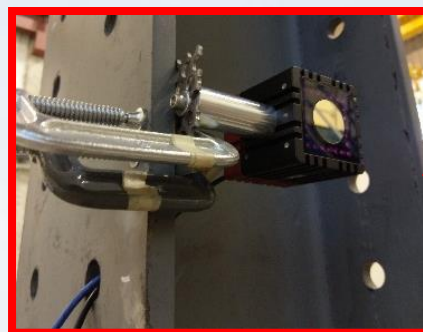


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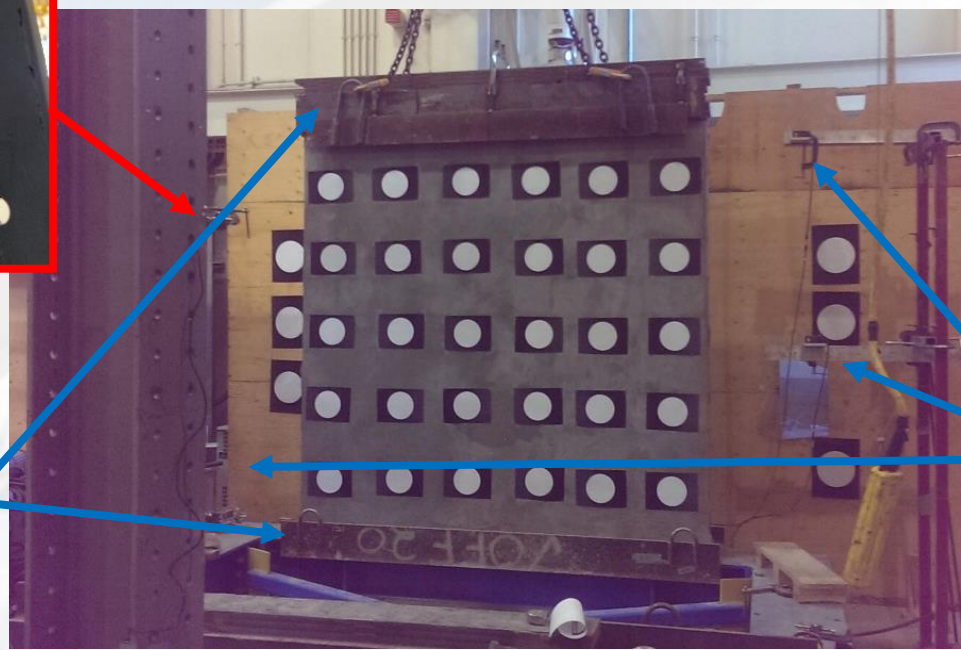




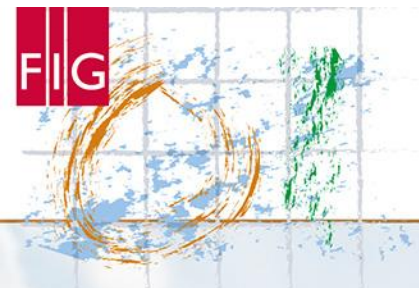
## Experiment Setup



2x accelerometer



3x LDS



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## SwissRanger SR4000 Data Sheet

- Absolute accuracy:  $\pm 10$  mm
- Repeatability: 4 - 7 mm  
(for central pixels)
- Non ambiguity range: 5.0 m
- Resolution: 176 x 144 pixel
- Field of view:  $69^\circ \times 56^\circ$
- Max. frame rate 50 Hz

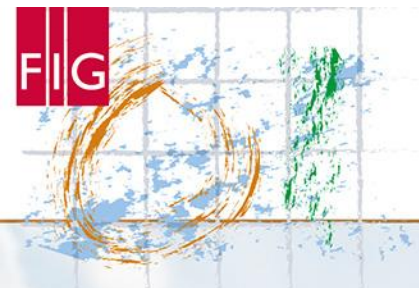
(MESA Imaging, 2011. SR4000 Data Sheet.)



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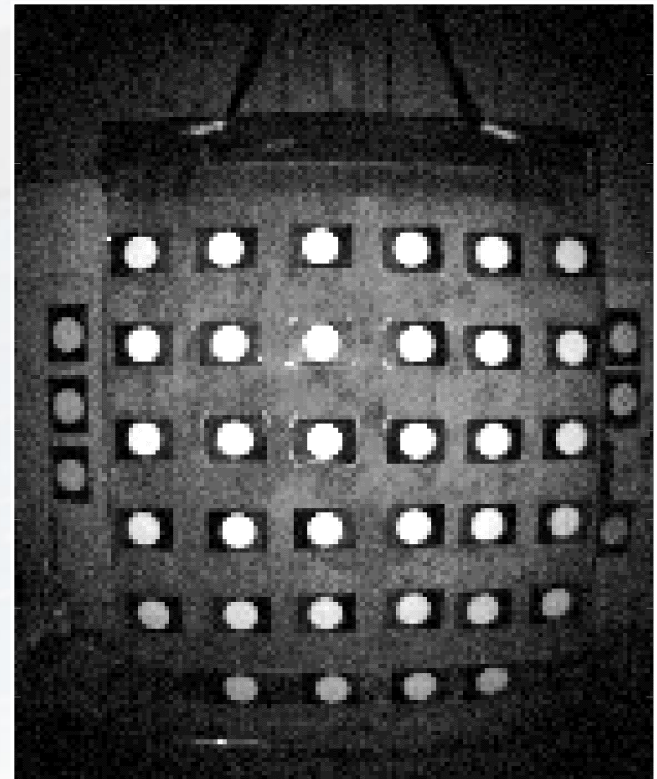
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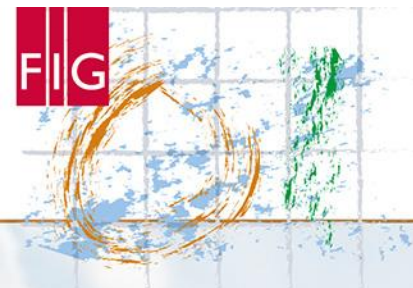
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## Processing

- Tracking targets in 2D amplitude image
- Compute 3D coordinates
- Moving average
- Averaging multiple targets (f.e. per row)  
→ under assumption of a rigid body





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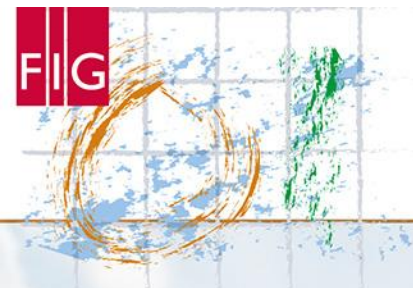
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Mean RMS from static tests:

	In-plane	Distance
Single point	2.5	9.7
Moving average	1.1	4.3
Average row	1.2	4.3
Both averages	0.5	1.9



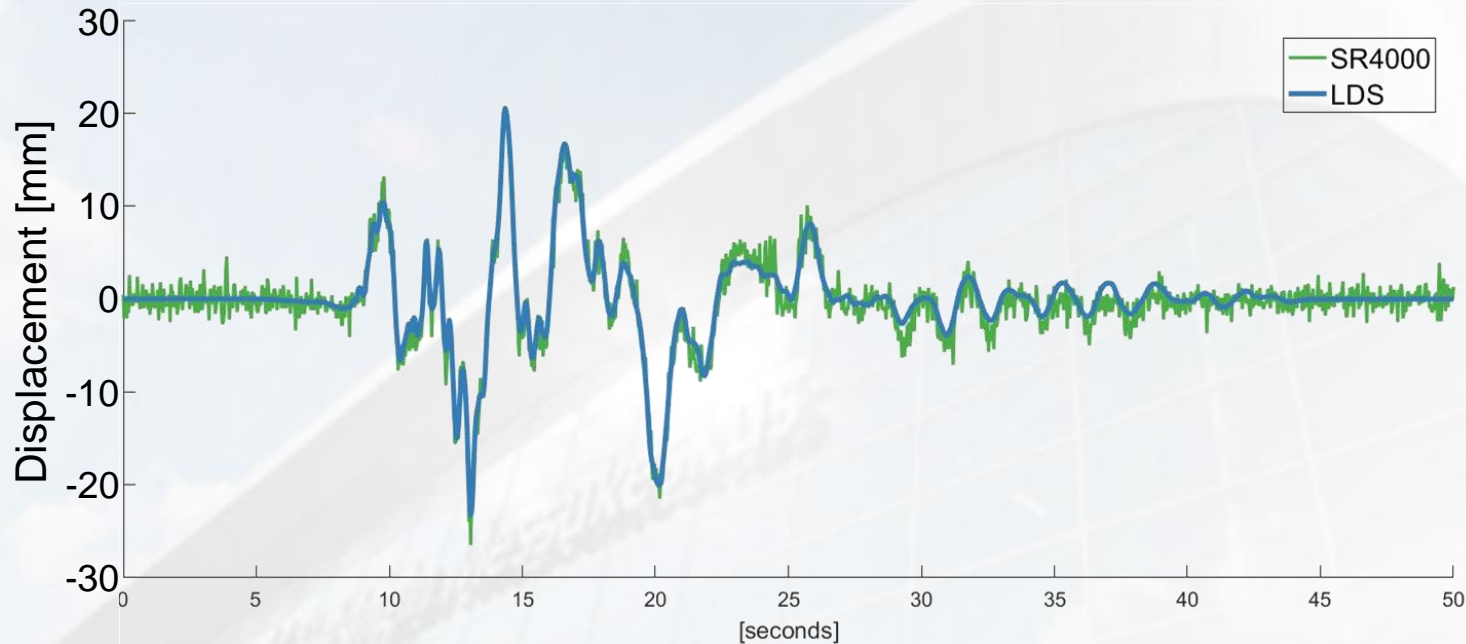
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## Comparison with Laser Displacement Sensor



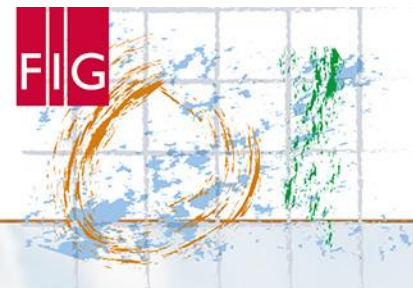
→ Standard deviation of differences 1.3 - 2.7 mm (In-plane)



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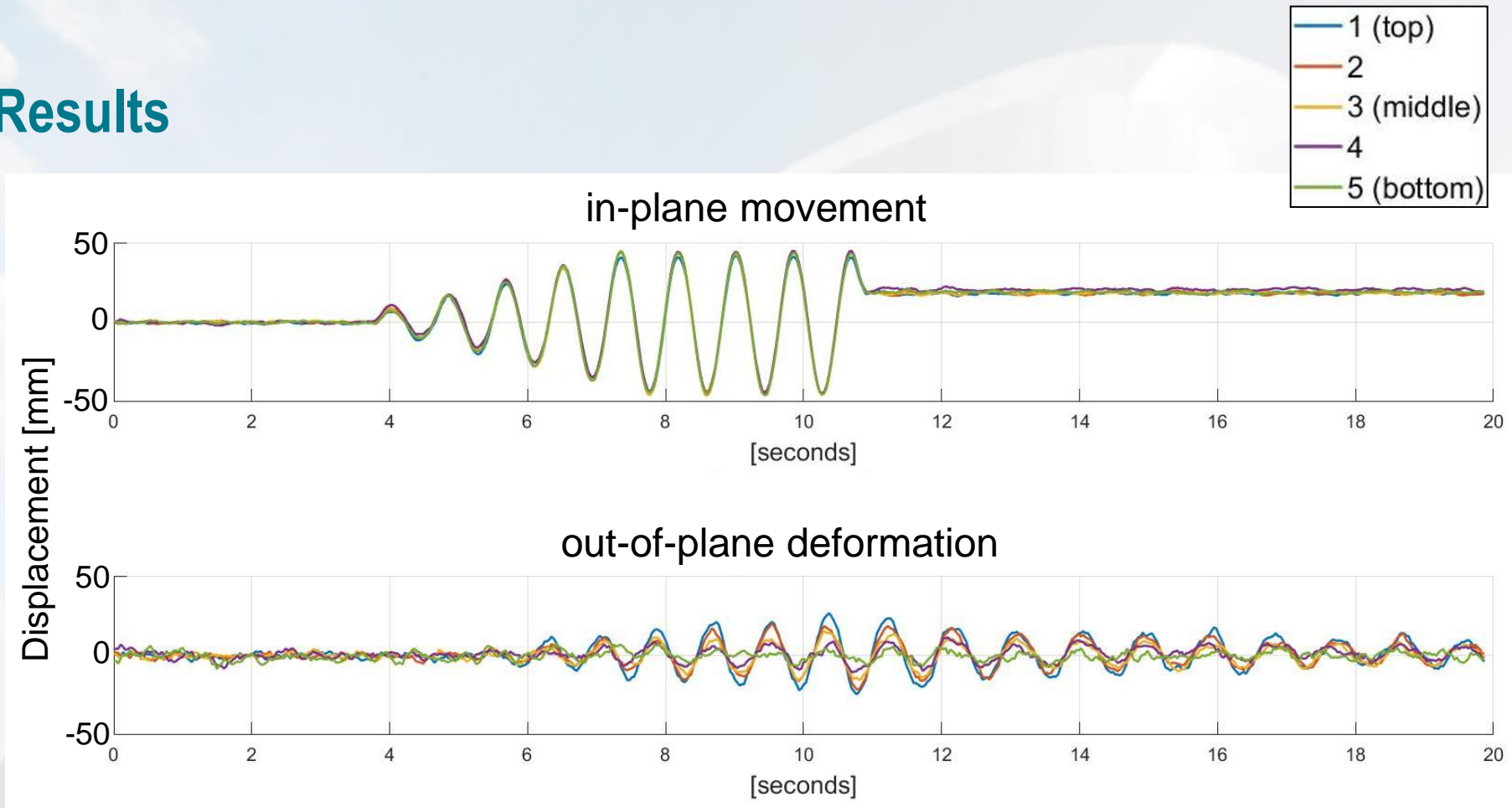
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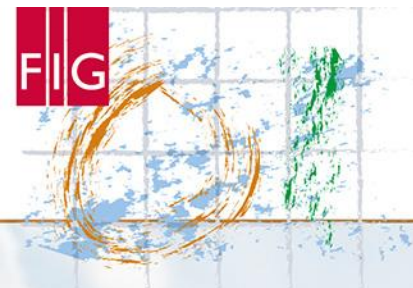
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## Results



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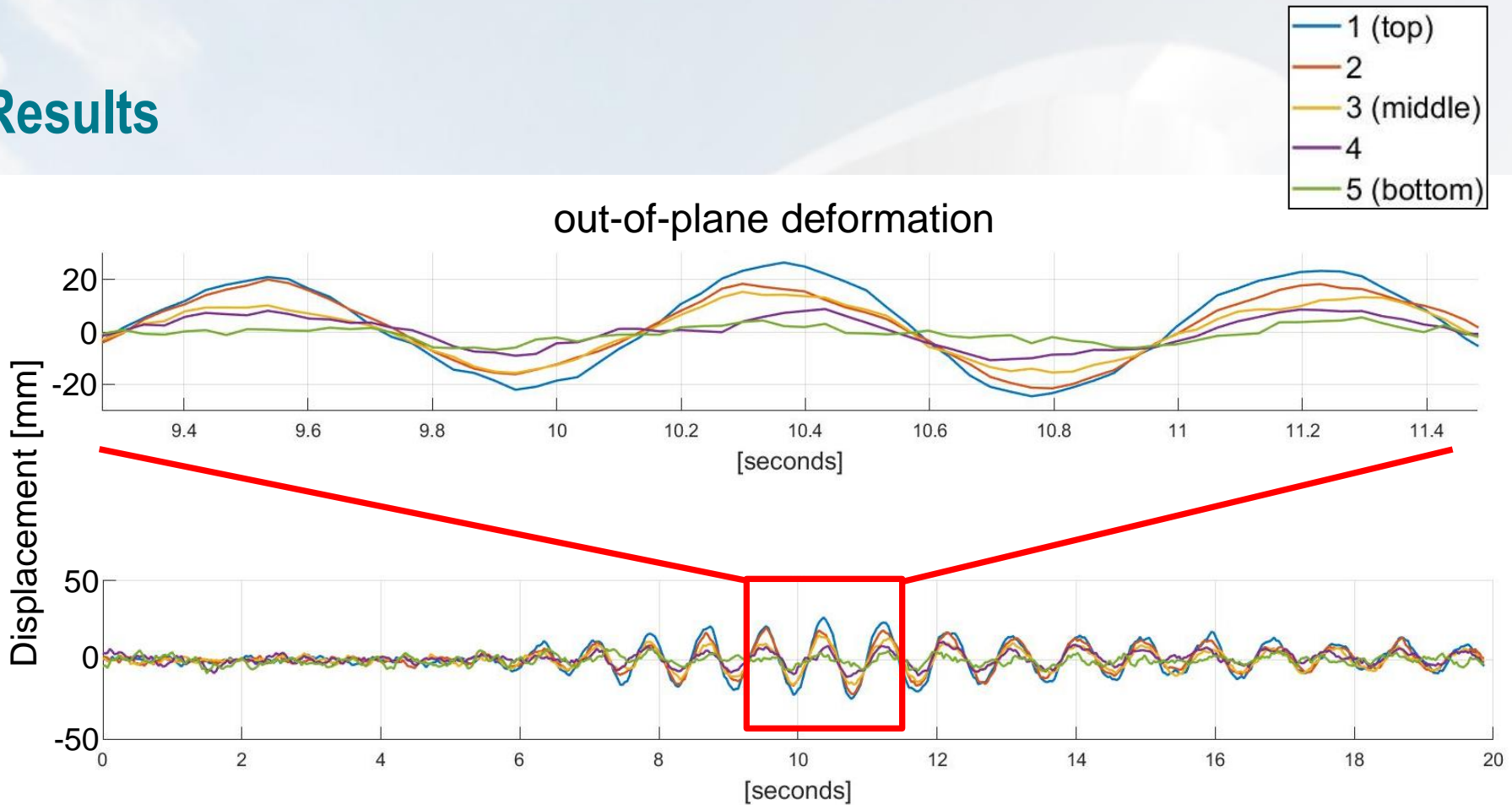
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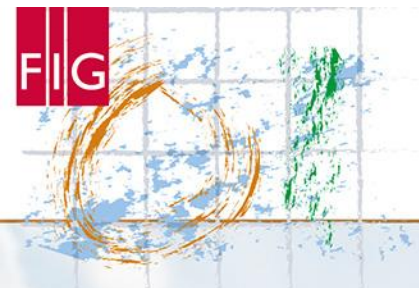
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## Results



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## Conclusions

- Range camera brings **additional information** to conventional sensors
  - Cover whole wall in **3D** with one sensor
  - **Safe distance** to the specimen
- Advantages compared to photogrammetry or laser scanning
  - Only **one sensor** necessary
  - **Active** Sensor
  - **Dynamic** measurements at video frame rate
- Limitation in accuracy and measurement frequency
- Challenge to extract additional information to compare walls and detect failure



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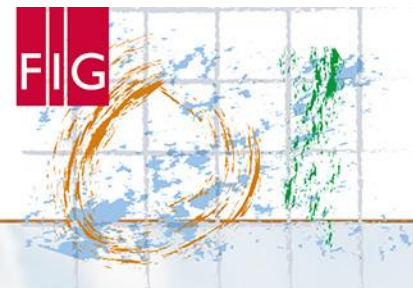


esri



Trimble





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Thank you!



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